Compiler Construction

Lecture 11 – Final Code Generation

Issues in Final Code Generation

- Final code generation is similar to intermediate code generation in some ways, but there are several issues that arise that do not occur in intermediate code generation:
 - Instruction Set
 - Memory Allocation
 - Register Allocation
 - Operating System Calls

Target Architecture

- Our target architecture is the Intel 8x86 family of processors.
- We first must consider:
 - Register Set
 - Flags
 - Floating Point Unit





AX (Accumulator) - favored for arithmetic opertions

BX (Base) - Holds base address for procedures and variables

CX (Counter) - Used as a counter for looping operations

DX (Data) - Used in mulitplication and division operations.

Segment Registers

<u>Segment registers</u> are used to hold base addresses for program code, data and the stack.

15		0
	CS	
15		C
	SS	
15		0
	DS	
15		C
	ES	

CS (Code Segment) - holds the base address for all executable instructions in the program

SS (Stack Segment) - holds the base address for the stack

DS (Data Segment) - holds the base address for variables

ES (Extra Segment) - an additional base address value for variable.

Index Registers

<u>*Index Registers*</u> contain the offsets for data and instructions.

<u>Offset</u> - distance (in bytes) from the base address of the segment.

BP	offset variab
SP	SP (St the top
SI	SI (So string
	DI (D

BP (Base Pointer) - contains an assumed offset from the SS register; used to locate variables passed between procedures.

SP (Stack Pointer) - contains the offset for the top of the stack.

SI (Source Index) - Points to the source string in string move instructions.

DI (Destination Index) - Points to the source destination in string move instructions.

Status and Control Registers

IP (Instruction Pointer) - contains the offset of IP the next instruction to be executed within the current code segment. 0 D Ι тΙ S Ζ Α Р С х х х Х Х х Х

Flags register contain individual bits which indicate CPU status or arithmetic results. They are usually set by specific instructions.

O = Overflow	S = Sign
D = Direction	Z = Zero
I = Interrupt	A = Auxiliary Carry
T = Trap	P = Parity
x = undefined	C = Carry

Flags

There are two types of flags: control flags (which determine how instructions are carried out) and status flags (which report on the results of operations.

- Control flags include:
 - *Direction* Flag (DF) affects the direction of block data transfers (like long character string). 1 = up; 0 down.
 - *Interrupt* Flag (IF) determines whether interrupts can occur (whether hardware devices like the keyboard, disk drives, and system clock can get the CPU's attention to get their needs attended to.
 - *Trap* Flag (TF) determines whether the CPU is halted after every instruction. Used for debugging purposes.

Status Flags

- Status Flags include:
 - *Carry* Flag (CF) set when the result of **unsigned** arithmetic is too large to fit in the destination. 1 = carry; 0 = no carry.
 - Overflow Flag (OF) set when the result of signed arithmetic is too large to fit in the destination. 1 = overflow; 0 = no overflow.
 - Sign Flag (SF) set when an arithmetic or logical operation generates a negative result. 1 = negative; 0 = positive.
 - Zero Flag (ZF) set when an arithmetic or logical operation generates a result of zero. Used primarily in jump and loop operations. 1 =zero; 0 = not zero.
 - Auxiliary Carry Flag set when an operation causes a carry from bit 3 to 4 or borrow (frombit 4 to 3). 1 = carry, 0 = no carry.
 - *Parity* used to verify memory integrity. Even # of 1s = Even parity; Odd # of 1s = Odd Parity

Floating-Point Unit

80-bit Data Registers

ST(0)
ST(1)
ST(2)
ST(3)
ST(4)
ST(5)
ST(6)
ST(7)

Opcode Register

48-bit Pointer Registers

FPU Instruction Pointer

FPU Data Pointer

16-bit Control Registers

Tag Register
Control Register
Status Register

Tag Register

tag 7	tag 6	tag 5	tag 4	tag 3	tag 2	tag 1	tag 0
-------	-------	-------	-------	-------	-------	-------	-------

tag	meaning
00	valid (finite nonzero number)
01	zero
10	invalid (infinite or NaN)
11	empty

Control Register

- The control register contains six exception masks and three control fields
- If one of the exception masks is cleared and that exception occurs, the program is suspended and the an interrupt is generated, which will either correct the problem is terminate the program.
- The control fields control rounding and the type of infinity used.



Coding The Stack Segment



Coding The Data Segment

_DATA SEGME	NT word	public	'data'
TestResult	dw	?	
x	dw	?	
У	dw	?	
_t47	dw	?	
_t48	dw	?	
_t49	dw	?	
_t51	dw	?	
_t55	dw	?	
_t56	dw	?	
_DATA ENDS			

Generating the Stack Segment Code

Generating the Data Segment Code

```
for (i = NUMTOKENS+2; i < tablesize(); i++) {</pre>
   if ((symclass(i) == sttempvar ||
                symclass(i) == stvariable)
                && getproc(i) == NUMTOKENS+1) {
          getlabel(i, label);
          if (data class(i) == dtinteger)
                fprintf(ofp, "%-10s
                                         dw"
                      "
                             ?\n", label);
          else
                fprintf(ofp, "%-10s
                                         dd"
                      "
                             ?\n", label);
   }
```



Activation Record



Processing Assignments

Processing Integer Addition

; \$_5 := \$_3 + \$_4 mov ax, _t47 add ax, _t48 jno Jump3 jmp iovrflo Jump3: mov _t49, ax

Processing Integer Subtraction

; \$_5 :	= \$_3 -	\$_4
	mov	ax, _t47
	sub	ax, _t48
	jno	Jump3
	jmp	iovrflo
Jump3:		
	mov	_t49, ax

Processing Integer Multiplication

; \$_4 :	= x * y	
	mov	ax, x
	imul	У
	jno	Jump2
	jmp	iovrflo
Jump2:		
	mov	_t50, ax

Processing Integer Division

; \$_3 :=	у/b	
	cmp	b, 0
	jne	Jump0
	jmp	divby0
Jump0:		
	mov	ax, y
	cwd ;co	nvert word to doubleword
	idiv	b
	jno	Jump1
	jmp	iovrflo
Jump1:		
	mov	_t51, ax

Processing Jumps

;	if \$	_6 !=	0	goto	_loop5	55
		Cm	р		_t51,	0
		je	je		Jump 6	
		jm	р		_loop5	55
Jump6:						
			• ••	• •••		
;	goto	_100	p54	4		
		jm	р		_loop	54

Processing Procedure Calls

;	arg x	
	mov	ax, offset x
	push	ax
;	call test	
	call	test

Beginning the Procedure

- Beginning a new procedure requires:
 - Saving the base pointer (where the current activation record begins)
 - Setting the old stack pointer to the new base pointer (where the new activation record begins)
 - Allocating space on the stack (in the new activation record) for local variables by adjusting the stack pointer.





Pushing the Return Address on the Stack



Dynamic Allocation of Local Variables



Code For the Procedure's Beginning

_TEXT SEGMENT test:

> push bp mov bp, sp

; Allocate space for local variables sub sp, 12

Local Variables In Assembler

```
; a := c
                   bx, word ptr [bp+2]
         mov
                    ax, [bx]
         mov
                   word ptr [bp-2], ax
         mov
; b := 8
                    ax, 8
         mov
         mov
                    word ptr [bp-4], ax
; \$_0 := a + b
         mov
                    ax, word ptr [bp-2]
         add
                    ax, word ptr [bp-4]
         jno
                    Jump9
                    iovrflo
         jmp
Jump9:
                    word ptr [bp-6], ax
         mov
```

Ending the Procedure

; Return space used by local variables mov sp, bp pop bp ret 2

TEXT ENDS